

Vivekanand College, Kolhapur. (Autonomous)
Department of Physics
Internal Examination Notice
2019-20

Date: 15/01/2020

All students of class B.Sc. I, B.Sc. II and B.Sc. III are hereby noticed that the second term internal evaluation examination is scheduled as per following time table.

Nature of question paper:

For B.Sc. I : Long answer question (Any one from given two questions) for 10 marks

Short answer question (Any two from given three questions) for 10 marks

For B.Sc. II : Long answer question (Any one from given two questions) for 10 marks

Short answer question (Any two from given three questions) for 10 marks

For B.Sc. II (Astro) : Long answer question (Any one from given two questions) for 10 marks

Short answer question (Any two from given three questions) for 10 marks

For B.Sc. III : Long answer question (Any one from given two questions) for 10 marks

Short answer question (Any two from given three questions) for 10 marks

Internal Evaluation Examination 2019-20.

SEM II, SEM IV and SEM VI

Time Table

Sr. No.	Class	Paper	Date	Time
1.	B.Sc. I	Paper II	27/01/2020	11:00 am to 12:00 pm
2.	B.Sc. II	Paper IV	27/01/2020	11:00 am to 12:00 pm
3.	B.Sc. II (Astrophysics)	Paper II	28/01/2020	11:00 am to 12:00 pm
4.	B.Sc. III	Paper VII (section I)	29/01/2020	11:00 am to 12:00 pm
		Paper VII (section II)		01:00 am to 02:00 pm
		Paper VIII (section I)	30/01/2020	11:00 am to 12:00 pm
		Paper VIII (section II)		01:00 am to 02:00 pm



HOD
 Head of the
 Department of Physics
 Vivekanand College, Kolhapur

Shri Swami Vivekanand Shikshan Sanstha's

Vivekanand College, Kolhapur

(Autonomous)

Department of Physics

Internal exam (2019-20)

B.Sc.III Sem VI

Attendance Sheet

Roll No.	Name Of The Student	Signature			
8001	Chougule Abhijeet Bajirao				
8002	Dalvi tejas chetan				
8003	Dinde Akash Sadashiv				
8004	Gaikwad Suraj Dhananjay				
8005	Ghosalkar Pranav Shankar				
8006	Harshad Sitaram Katroot				
8007	Jadhav Pratiksha Harish				
8008	Joshi Sourabh Kiran				
8009	Kamble Prasad Vilas				
8010	Kumbhar Prathmesh Mallikarjun	P.M. Kumbhar	P.M. Kumbhar	P.M. Kumbhar	P.M. Kumbhar
8011	Kumbhar Jayvant Rajaram				
8012	Manasi Vinayak Kulkarni				
8013	Manasi Kahnderao Jagadale				
8014	Nalavade Ankita Amar				
8015	Paranjape Anish Shriram				
8016	Patil Amruta Bhuigonda				
8017	Patil Sujata Anandrao				
8018	Patil Jeevan Maruti				
8019	Patil Tejaswini Krishna				
8020	Paul Jonathan Sanjay				
8021	Potdar Aishwarya Sharad				
8022	Radhika Baburao Shinde				
8023	Ragini Jayprakash Benake				
8024	Sandhya Sudhakar Dingane				
8025	Sawant Rohit Ramchandra				
8026	Sourabh Vijay Ghatage				
8027	Sujit Dinkar Katale	S.P.K.	S.P.K.	S.P.K.	S.P.K.
8028	Swaranjali Sanjay Shinde				
8029	Swarupa Baburao Dhavale				
8030	Tanvi Vikas Mohite				
8031	Tibile Rohan Arjun				
8032	Tushar Arvind Patil				



8033	Yogita Vishnu Zinenge	Yogita	Yogita	Yogita	Yogita
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Internal Examiner..... 



Vivekananda College Kolhapur (Autonomous).
Department of Physics: Internal examination 2021-22

B.Sc. III Semester V

Subject: Electrodynamics and Electromagnetic Waves

Marks: 20 (Each question carry one mark)

Time : 20 min

Q.1 Attempt any ONE

(10)

1. Derive Poisson's equations and their physical significance
2. Derive Laplace's equations and their physical significance

Q.2 Attempt any TWO

(10)

1. Discuss Laplace's equation in one dimension and its solution (Cartesian co-ordinate).
2. Derive an expression for motion of charged particle in uniform electric field.
3. Derive an expression for uniform magnetic field.



Name: Jeevan Maruti Patil

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- शिक्षणमहर्षी डॉ. बापूजी साबुळे

Signature of
Supervisor



Shri Swami Vivekanand Shikshan Sanstha's VIVEKANAND COLLEGE (Autonomous), KOLHAPUR

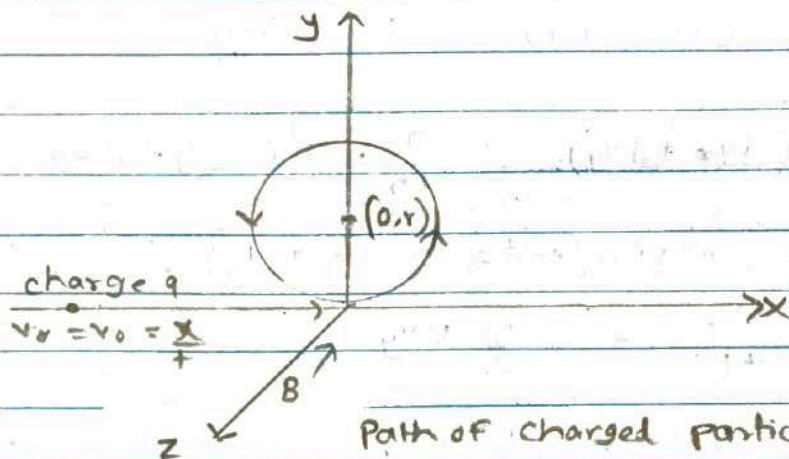
Class Bsc. III Div. 18/20 Roll No. 8018

Suppliment No. _____ Subject Physics XX

Test / Tutorial No. Internal Exam

- Q. Derive an expression for motion of charge particle in constant uniform magnetic field.

Let us consider a charge particle of charge q and mass m moving in constant magnetic field B .



Path of charged particle in uniform B field

Under the action of these magnetic field, the charge particle moves in a plane perpendicular to B i.e. in $x-y$ plane. The force acting on a charged particle because of magnetic field B is.

$$F = q(v \times B) \quad \text{--- (1)}$$

Let, i, j, k be the unit vectors along x, y, z axes respectively. \therefore if v_x and v_y are component of velocities of the charged particle along x and y directions respectively

$$v = v_x i + v_y j \quad \text{--- (2)}$$

According to Newton's second law of motion, force acting on the charged particle is

$$F = m \cdot \frac{dv}{dt}$$



$$\therefore \frac{dv}{dt} = i\omega dt \quad \text{--- (9)}$$

Integrating above eqn for velocity & time

$$\int_{v_0}^v \frac{dv}{v} = \int_0^t i\omega dt$$

$$\therefore [\log v]_{v_0}^v = i\omega [t]_0^t$$

$$\therefore \log v - \log v_0 = i\omega t \quad \text{--- (10)}$$

$$\log \left(\frac{v}{v_0} \right) = i\omega t$$

$$\therefore \frac{v}{v_0} = e^{i\omega t}$$

$$\therefore v = v_0 e^{i\omega t}$$

But $v = v_x + iv_y$

and $e^{i\omega t} = \cos \omega t + i \sin \omega t$

equation becomes

$$(v_x + iv_y) = v_0 (\cos \omega t + i \sin \omega t) \quad \text{--- (11)}$$

comparing real & imaginary parts on both sides

$$v_x = v_0 \cos \omega t \quad \text{--- (12)}$$

$$v_y = v_0 \sin \omega t \quad \text{--- (13)}$$

squaring & adding equation

$$v_x^2 + v_y^2 = v_0^2 \cos^2 \omega t + v_0^2 \sin^2 \omega t$$

$$v_x^2 + v_y^2 = v_0^2$$

$$\sqrt{v_x^2 + v_y^2} = v_0$$

$$v = v_0$$

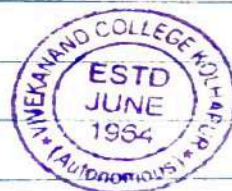
Further,

$$v_x = dx/dt$$

$$\therefore \frac{dx}{dt} = v_0 \cos \omega t$$

$$dx = v_0 \cos \omega t \cdot dt$$

Integrate above equations



$$\int_0^x dx = \int_0^t v_0 \cos \omega t \cdot dt$$

$$x = \frac{v_0}{\omega} \sin \omega t + k \quad \text{--- (14)}$$

k is constant of integration, At $t=0$, $x=0$ and $y=0$

$$v_y = dy/dt$$

$$\therefore dy/dt = v_0 \sin \omega t$$

$$dy = v_0 \sin \omega t \cdot dt$$

Integrate above eqn

$$\int_0^y dy = \int_0^t v_0 \sin \omega t$$

$$y = -\frac{v_0}{\omega} \cos \omega t + k \quad \text{--- (15)}$$

At $t=0$, $y=0$ then

$$0 = -v_0/\omega + k$$

$$\therefore k = v_0/\omega$$

Hence equation (15) changes to

$$y = -\frac{v_0}{\omega} \cos \omega t + v_0/\omega$$

$$\therefore y = \frac{v_0}{\omega} - \frac{v_0}{\omega} \cos \omega t \quad \text{--- (16)}$$

But $\frac{v_0}{\omega} = r = \text{radius of path taken by charged particle}$

$$x = r \sin \omega t \quad \text{--- (17)}$$

$$y = r - r \cos \omega t \quad \text{--- (18)}$$

$$y - r = -r \cos \omega t \quad \text{--- (19)}$$

Squaring and adding eq (18) and (19)

$$x^2 = (y-r)^2 = r^2 \sin^2 \omega t + r^2 \cos^2 \omega t$$

$$x^2 + (y-r)^2 = r^2 \quad \text{--- (20)}$$

this eqn is equation of circle with centre (0, r) radius r .

\therefore Thus motion of charged particle in B field is circular



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Class B.Sc.-III

Div _____

Roll No. 8019

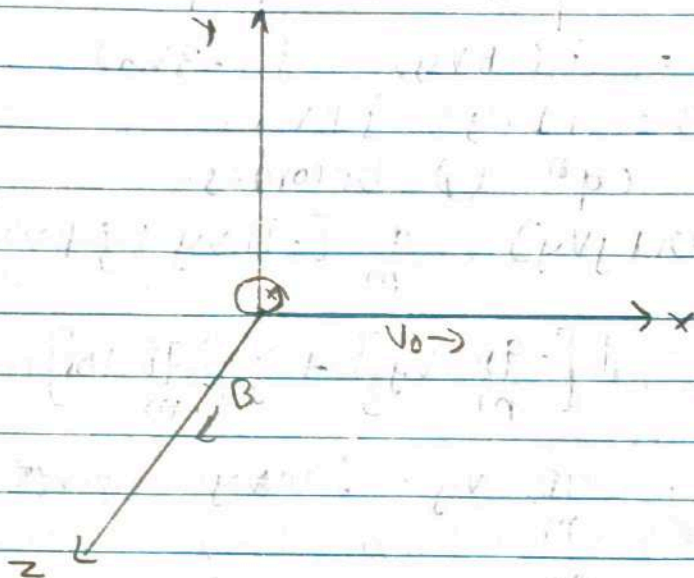
Suppliment No. _____

Subject physics

Test / Tutorial No. _____

Internal Exam - 1
Surprise

Ans - 1 The motion of P charged particle in a constant uniform magnetic field.



Consider charge particle q of mass m moving with velocity v_0 along the x axis. Let it enters in a constant uniform magnetic field B directed along $-ve 'z'$ direction. Due to magnetic field particle experience magnetic force F_m & it is given by.

$$F_m = q(v \times B) \quad \text{--- (1)}$$

Where v = velocity of particle in m.f.

Under the act of magnetic force F_m the particle moves in a direction \perp to B & v . i.e the particle moves in x, y plane with velocity v & it is given by



$$\mathbf{v} = i v_x + j v_y \quad \text{--- (1)}$$

Acc to Newton's 2nd law
we have,

$$F_m = m a = \frac{m d\mathbf{v}}{dt} \quad \text{--- (2)}$$

We have $\mathbf{v} = i v_x + j v_y$

$$\mathbf{B} = -k\mathbf{B}$$

$$\therefore \mathbf{v} \times \mathbf{B} = \begin{vmatrix} i & j & k \\ v_x & v_y & 0 \\ 0 & 0 & B \end{vmatrix}$$

$$= i(-B v_y) - j(-B v_x)$$

$$\mathbf{v} \times \mathbf{B} = i B v_y + j B v_x$$

hence eqn (2) becomes.

$$\frac{d}{dt} [i v_x + j v_y] = \frac{q}{m} [-i B v_y + j B v_x]$$

$$= i \left[-\frac{qB}{m} v_y \right] + j \left[\frac{qB}{m} v_x \right]$$

$$\frac{dv_x}{dt} = -\frac{qB}{m} v_y = -\omega v_y \quad \text{--- (3)}$$

$$\frac{dv_y}{dt} = \frac{qB}{m} v_x = \omega v_x \quad \text{--- (4)}$$

where $\omega = \frac{qB}{m}$

Multiplying eqn (3) by imaginary j and adding in eqn (4)

$$\frac{dv_x}{dt} + i \frac{dv_y}{dt} = -\omega v_y + i \omega v_x$$

$$\frac{d}{dt} [v_x + i v_y] = i \omega [v_x + i v_y]$$

put $v_x + i v_y = v e^{i\theta}$

we get.



eqn ⑦ is a diffⁿ eqn of the 1st order.

$$\frac{dv}{v} = i\omega dt.$$

Integrating at both side.

$$\int_{v_0}^v \frac{dv}{v} = \int i\omega dt$$

$$[\log v]_{v_0}^v = i\omega t.$$

$$\log \frac{v}{v_0} = i\omega t$$

$$\frac{v}{v_0} = e^{i\omega t}.$$

$$v = v_0 e^{i\omega t}.$$

Substituting value of v , we get

$$V_x + iV_y = v_0 e^{i\omega t}.$$

$$V_x + iV_y = v_0 [\cos \omega t + i \sin \omega t]$$

$$V_x + iV_y = v_0 \cos \omega t + i v_0 \sin \omega t.$$

Equating real terms & imaginary terms.

$$V_x = v_0 \cos \omega t.$$

$$V_y = v_0 \sin \omega t.$$

Consider

$$V_x = v_0 \cos \omega t.$$

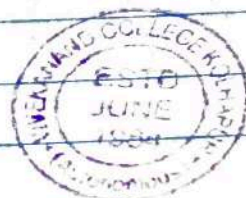
$$\frac{dx}{dt} = v_0 \cos \omega t$$

$$dx = v_0 \cos \omega t dt$$

Integrating at both sides.

$$\int dx = v_0 \int \cos \omega t dt.$$

$$x = v_0 \frac{\sin \omega t}{\omega t}.$$



Now consider

$$V_y = V_0 \sin \omega t$$

$$\frac{dy}{dt} = v_0 \sin \omega t.$$

$$dy = v_0 \sin \omega t \, dt.$$

on integrating

$$s dy = v_0 \int \sin \omega t dt.$$

$$y = \frac{v_0}{\omega} [\cos \omega t]'_0^0 = \frac{v_0}{\omega} [\cos \omega t - 1]$$

$$y = r \cos \theta = r$$

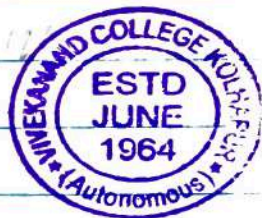
$$y = -r - r \cos \omega t \quad \text{--- (8)}$$

$$y - x = +x \cos \omega t - \quad (9)$$

squaring & adding eqⁿ (8) & (9) we get.

$$x^2 + (y-x)^2 = r^2 \quad \text{For } r = 1$$

Above eqⁿ is eqⁿ at circle which given trajectory of particle is circular.



Vivekananda College Kolhapur (Autonomous).
Department of Physics: Internal examination 2019-20
B.Sc. III Semester V
Subject: Energy Studies and Materials Science

Marks: 20 (Each question carry one mark)

Time : 20 min

Q.1 Attempt any ONE

(10)

1. Discuss briefly wind energy, wind energy chains, wind energy quantum
2. Write a note on Efficiency factor of wind turbine(P-H graph).

Q.2 Attempt any TWO

(10)

3. Write a note on Classification of energy resources.
4. What are the types of types of a wind turbine generator unit.
5. Define the factors : a) wind energy chains, b) wind energy quantum, c) wind power density, d) power of wind turbine for a given incoming wind velocity



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VIVEKANAND COLLEGE, KOLHAPUR (AUTONOMOUS)

SUPPLIMENT

Suppliment No. :

Roll No. : 8525

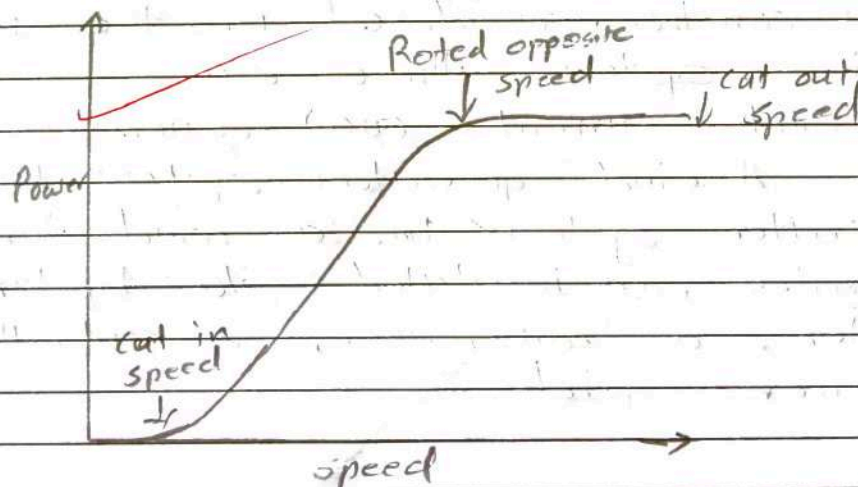
Class : B.Sc. III, sem-V

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of
Supervisor

Subject : (Energy studies and material sciences)
Test / Tutorial No. : Internal exam
Div. :

Q.1

- 27 The power output of wind turbine depends on where it is located, as well as the physical characteristics of the turbine itself. It is highly unlikely that the wind speed will be steady in any location, and \therefore the output will vary in line with the speed at any one time. This is where a wind turbine power curve can help to estimate current and near future output.



At very low wind speeds, there is insufficient torque exerted by the wind on the turbine blades to make them rotate. However, as the speed increases, the wind turbine will begin to rotate and generates electrical power.

The speed at which the turbine first starts to rotate and generate power is called the cut-in-speed, and is typically between 3 and 4 meters per second.

The available power in a stream of wind of the same cross sectional area as the wind turbine can easily be shown to be

$$\frac{1}{2} \rho A v^3$$

If the wind speed v is in meter per second, the density ρ is in kilogram per cubic meter and the rotor diameter d is in meters then the available power in watts.

Q-2

2) There are four types of wind turbines generator which can be considered for the various wind turbine systems those are

1. Direct current (DC) generators

A wind generator system has a wind turbine, a DC generator, an insulated gate bipolar transistor inverter, a transformer, a controller, and a power grid

2. AC Synchronous Generator :-

AC Synchronous wind turbine generators can take constant or DC excitation from either permanent magnets or electromagnets.

08/ 3. Switched Reluctance wind Turbine Generator
switched reluctance wind turbine generators have features such as strong rotor and stator.



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VIVEKANAND COLLEGE, KOLHAPUR (AUTONOMOUS)

SUPPLIMENT

Suppliment No. :

Roll No. : 8513

Class : B.Sc-III, Sem-V

Signature
of
Supervisor

Subject : Energy Studies and Material
Science

Test / Tutorial No. : Internal Exam

Div. :

19
20

Q.2}

3) (a) Wind energy chains- The wind power value chain incorporates five main stages: materials, components, manufacture, logistics, development and operations.

(b) Wind energy Quantum- Wind energy is a form of solar energy, meaning that it originates from the sun. The sun heats the atmosphere unevenly so that the temperature varies at different places.

(c) Wind Power Density - Wind power density is a quantitative measure of wind energy available at any location. It is the mean annual power available per square meter of swept area of a turbine.

(d) Power of wind turbine- Wind turbines convert the kinetic energy in the wind into mechanical power. The mechanical power can be used for specific tasks.



Q. 2)

2) There are four types of wind turbines generator which can be considered for the various wind turbine systems those are:

1. Direct Current (DC) generators-

A wind generator system has a wind turbine, a DC generator, an insulated gate bipolar transistor inverter, a transformer, a controller, and a power grid.

2. AC Synchronous Generator -

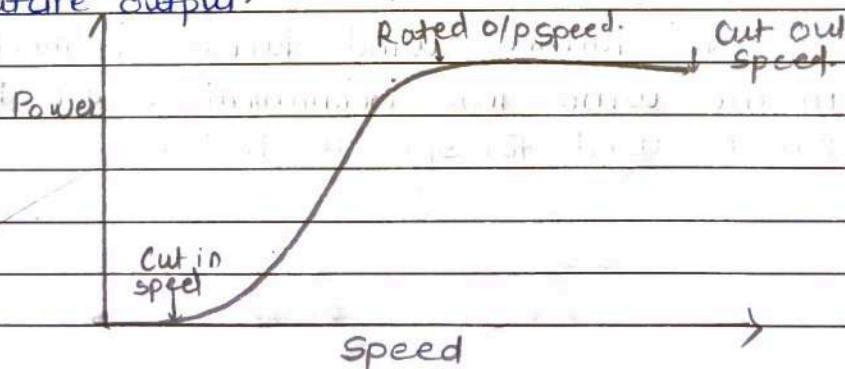
AC synchronous wind turbine generators can take constant or DC excitations from either permanent magnets or electromagnets.

3. Switched Reluctance Wind Turbine Generator -

Switched reluctance wind turbine generators have features such as strong rotor and stator.

Q. 1)

2) The power output of a wind turbine depends on where it is located, as well as the physical characteristics of the turbine itself. It is highly unlikely that the wind speed will be steady in any location, and therefore the output will vary in line with the speed at any one time. This is where a wind turbine power curve can help to estimate current and near future output.

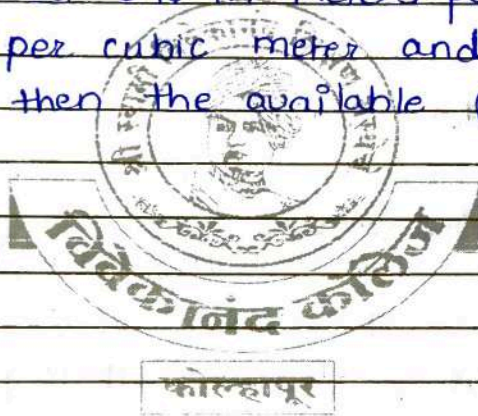


At very low wind speeds, there is insufficient torque exerted by the wind on the turbine blades to make them rotate. However, as the speed increases, the wind turbine will begin to rotate and generate electrical power.

The speed at which the turbine first starts to rotate and generate power is called the cut-in speed, and is typically between 3 and 4 meters per second.

The available power in a stream of wind of the same cross-sectional area as the wind turbine can easily be shown to be: $\frac{1}{2} \rho U^3 \frac{\pi d^2}{4}$

If the wind speed U is in meters per second, the density ρ is in kilograms per cubic meter and the rotor diameter d is in meters then the available power in watts.



Vivekananda College Kolhapur (Autonomous).
Department of Physics: Internal examination 2019-20

B.Sc. III Semester VI

Subject: Nuclear and Particle Physics

Marks: 20 (Each question carry one mark)

Time : 20 min

Q.1 Attempt any ONE

(10)

1. Explain the Cyclotron- construction, working, theory- expression for energy of cyclotron and its limitations
2. Explain the Synchro-cyclotron construction, working and its advantages, disadvantages.

Q.2 Attempt any TWO

(10)

1. Discuss the principle of Principle of phase stable orbits
2. Derive the expression for Betatron expression of energy gain.
3. Write a note on Need of accelerators.



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SUPPLIMENT

Suppliment No. :

Roll No. : 8509

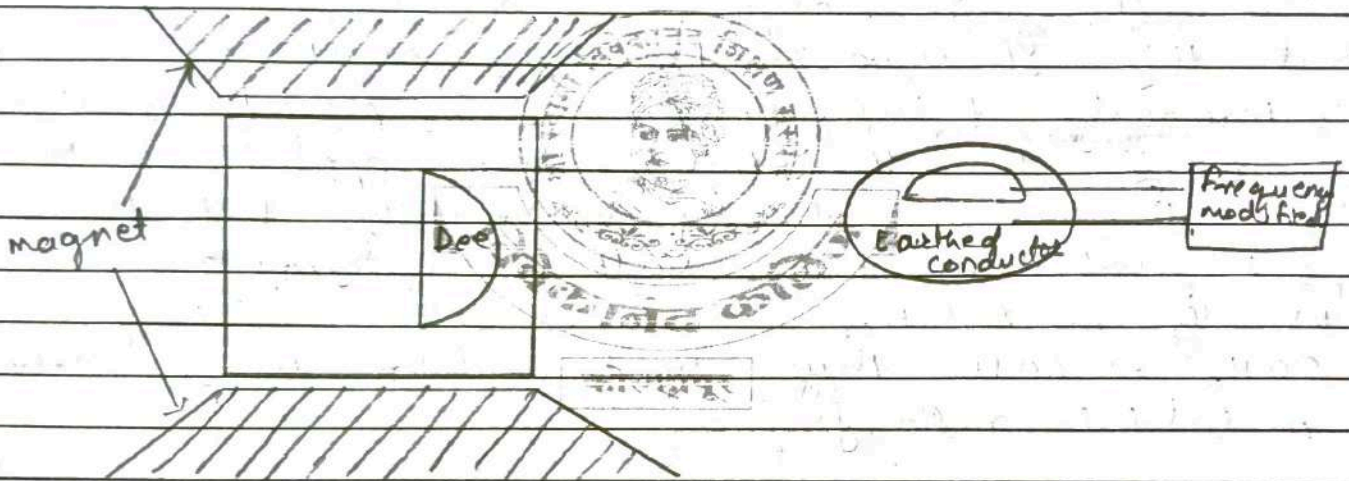
Class : BSc III sem V

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Subject : Nuclear and Particle
Physics.

Test / Tutorial No. : Internal Exam

Div. :



Synchrocyclotron is basically cyclotron with some modification viz,

1) The size of the dees is fairly large as maximum obtainable energy is very large & hence the pole-piece diameters are also very large.

2) Instead of simple radio frequency oscillator, the alternating voltage is obtained from a frequency modulated supply.



In Berkeley Synchrocyclotron, the modulated frequency is varied from 12.6 MHz to 9.0 MHz.

- 3) Only one dee is used with an earthed conductor on the opposite side of opening of the dee.

Working:- To impart energy to the particle, the frequency of an alternating voltage between dees is decreased when the particle goes into a phase stable orbit characterised by a large radius with gain energy.

But this decrease in frequency must be done continuously & very slowly as compared to the frequency of alternating voltage applied to the diode decreases slowly & continuously, but the peak value of the voltage remains the same. Usually, modulation is done at

50 Hz or 60 Hz. Thus, syndesychron uses a frequency modulated radio frequency.

Advantages of synchrocytation

- 1) As it is based on the principle of phase stable orbit the relativistic mass increase is taken care of & therefore there is no need to restrict the no. of revolutions & hence the potential difference required between the dees may be very low.
- 2) Large electric fields in the gap required for focusing and accelerating the particles in cyclotron are not demanded so, usually only one dee is used.



used. This ample space is made available in the evacuated steel tank.

3) In Berkeley 184 inch synchrocyclotron, the proton energies upto 300 MeV have been achieved.

Q2

1) The principal of principle of phase stable orbit

Consider a particle of relativistic mass

$$m = m_0 \left(1 - \frac{v^2}{c^2}\right)^{-1/2}$$

and charge e , moving in an orbit of radius r , under the influence of magnetic field B .

$$\frac{mv^2}{r} = Bev \quad \text{--- (1)}$$

Angular velocity $\omega = \frac{v}{r} = \frac{Be}{m}$

The angular velocity ($\omega = \frac{2\pi}{T}$) will be constant

for particle with constant mass m , which is the principle of cyclotron.

$$\omega = \frac{Bec^2}{mc^2} = \frac{Bec^2}{m_0c^2 + E_k} \quad \text{--- (2)}$$

where m_0c^2 is rest mass energy & E_k is kinetic energy of the particle.



Thus the angular velocity of the particle in a constant magnetic field, decreases with increase in the kinetic energy & hence the phase relationship required for cyclotron principle will be upset. However a particle with a definite kinetic energy E_k will move in a stable orbit with constant angular velocity ω which is also the angular frequency of the alternating voltage between the dees. Such an orbit where phase-stability is maintained

Now it can be seen that the particle with a specific energy can be maintained in a phase-stable orbit, if every E_k will move in a stable orbit with constant angular velocity ω which is also the angular frequency of it, when the instantaneous potential difference across the dees is zero & about to become decelerating.



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VIVEKANAND COLLEGE, KOLHAPUR (AUTONOMOUS)

SUPPLIMENT

Signature
of
Supervisor

Subject : Nuclear and Particle physics

Test / Tutorial No. : Internal

Div. :

Suppliment No. :

Roll No. : 8522

Class : B.sc. Sem V

Synchrocyclotron -

Construction -

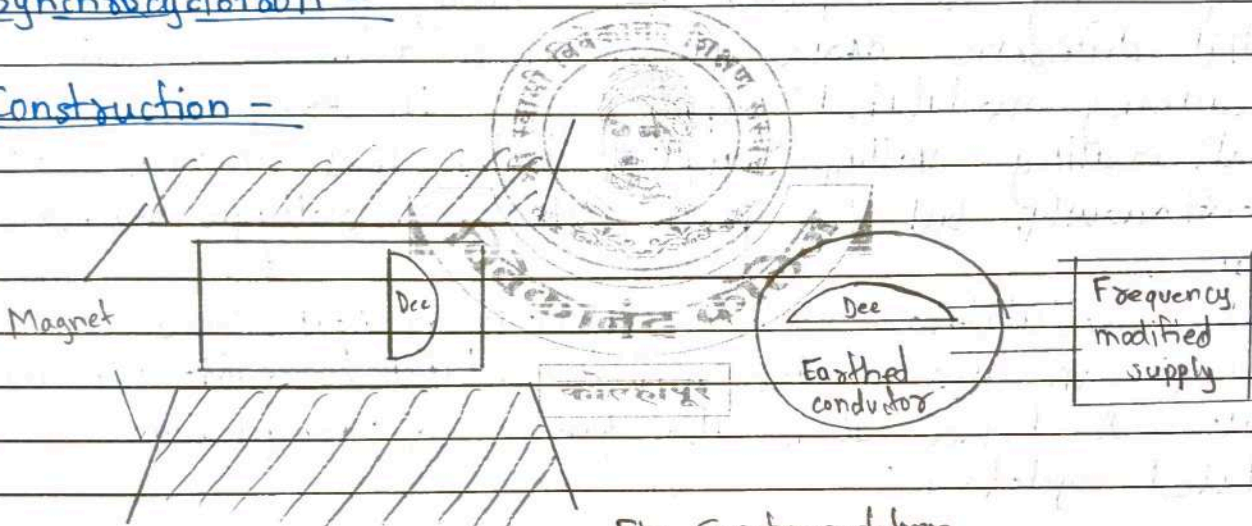
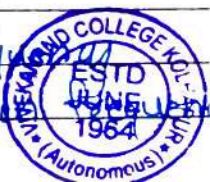


Fig. Synchrocyclotron

Synchrocyclotron is basically a cyclotron with some modifications viz.

- 1) The size of dees is fairly large as maximum obtainable energy is very large & hence the pole-piece diameters are also very large. Therefore, huge magnets weighing several tonnes are used.
- 2) Instead of simple radio frequency oscillator, the alternating voltage is obtained from a frequency modulated supply. In Berkeley synchrocyclotron, the modulated frequency is varied from 12.5 MHz to 9.0 MHz at a modulation



of 120 Hz.

⑤ Only one dee is used with an earthed conductor on the opposite side of opening of the dee as shown in the above fig.

Working-

① To impart energy to the particle, the frequency of an alternatively voltage between dees is decreased, when the particle goes into phase stable-orbit characterised by a large radius with gain in energy.

② But this decrease in frequency must be done continuously & very slowly as compared to frequency of alternating potential difference across dees. This is achieved by using a frequency modulated supply whose frequency of the alternating voltage applied to the dees decrease slowly & continuously, but the peak value of voltage remains the same.

③ Usually modulation is done at 50 Hz or 60 Hz. Thus synchrocyclotron uses a frequency modulated radio frequency oscillator & hence it is also known as 'frequency modulated cyclotron'.

Advantages

① As it is based on principle of phase-stable orbits, the relativistic mass increase is taken care of and therefore there is no need to restrict the no. of revolutions & hence the potential difference required betⁿ dees may be very small. Usually it is about 15 kV at peak of alternating voltage.

② Large electric fields in gap required for focusing and accelerating particles in cyclotron are no longer demand. So usually only 1 dee is used. Thus ample space is made



available in evacuated steel tank for setting different targets or other apparatus.

(3) In Berkeley 184 inch synchrocyclotron the proton energies upto 300 MeV have been released.

Disadvantages -

(1) It can't be used to accelerate electron.

2.4] Phase - stable Orbit Condition -

(i) Consider a particle of relativistic mass $m = M_0 \left(\frac{1-v^2}{c^2} \right)^{-\frac{1}{2}}$ and charge e , moving in an orbit of radius r under the influence of magnetic field B .

$$\frac{mv^2}{r} = Bev \quad \text{--- (1)}$$

$$\text{Angular velocity } \omega = \frac{v}{r} = \frac{Be}{m}$$

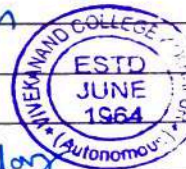
(ii) The angular velocity $\left(\omega = \frac{2\pi}{T} \right)$ will be constant for particles with constant mass m , which is the principle of cyclotron. But when m increases relativistically then,

$$\omega = \frac{Bec^2}{mc^2} = \frac{Bec^2}{mc^2 + E_k} \quad \text{--- (2)}$$

(3) When mc^2 is rest mass energy & E_k is kinetic energy of particle.

(4) Thus, the angular velocity of particle in constant magnetic field decreases with increase in kinetic energy & hence phase relationship required for cyclotron principle will be upset.

However, a particle with a definite kinetic energy E_k will move in stable orbit with constant angular velocity ω which is also angular frequency of



alternating voltage betⁿ dees.

⑥ Such an orbit whose phase stability is maintained is called a phase-stable-orbit.

⑦ Now it can be seen that the particle with specific ene. can be maintained in phase-stable-orbit if every time it crosses the gap between dees when the instantaneous potential difference across the dees is zero and about to become decelerating.

⑤



Vivekananda College Kolhapur (Autonomous).
Department of Physics: Internal examination 2021-22

B.Sc. III Semester V

Subject: Solid State Physics

Marks: 20 (Each question carry one mark)

Time : 20 min

Q.1 Attempt any ONE (10)

1. Discuss Reciprocal lattice, Properties of reciprocal lattice.
2. Derive Bragg's law in reciprocal Lattice (Ewald's construction).

Q.2 Attempt any TWO (10)

1. Define Powder method of X- ray diffraction.
2. Write a note on Miller indices
3. Derive packing fraction of HCP structure.



PRN No. 2015015500159146



VIVEKANAND COLLEGE, KOLHAPUR

Jr. Supervisor's Sign :

Students Sign : P. Manuach

Seat No. 8820

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Information to be filled by Student (विद्यार्थ्याने भरावयाचा रकाना)

Day and Date : Tuesday, 23-1-2018

Language of Answer : English

Examination : Internal Exam

Question Paper Code No : _____

Subject : Physics

Paper No. : 88VI

Section : _____

Q. No.	Examiner Marks	Moderator Marks
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Total	<u>25</u>	
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Q. No.				TOTAL				TOTAL
Marks								

3



Que. 1.

- i) a) 12 ✓
- ii) a) $a/2$ ✓
- iii) a) (643) ✓
- iv) c) reflection ✓
- v) b) inversely proportional to volume of unit cell of direct lattice ✓



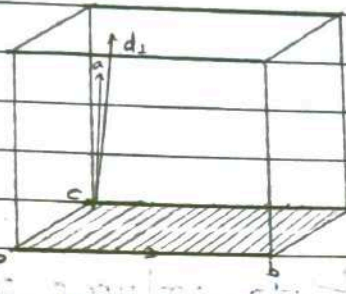
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Marks								

Q. No.



Que. 2.

1) Relation between direct lattice and reciprocal lattice :-



The relation between direct lattice & reciprocal lattice can be calculated.

Let, V be the volume of unit cell.

Volume = Area (shaded region) \times height

$$\text{volume} = \text{area} \times d_1$$

$$\therefore d_1 = \frac{\text{volume}}{\text{area}}$$

$$\therefore \frac{1}{d_1} = \frac{\text{area}}{\text{volume}}$$

$$\therefore \frac{\vec{n}}{d_1} = \frac{\vec{a}}{\vec{a} \cdot (\vec{b} \times \vec{c})} \times \vec{b}_{100}$$

As $\vec{a} \cdot (\vec{b} \times \vec{c})$ be the volume.



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Q. No.



$$\therefore \sigma_{100} = \frac{\vec{b} \times \vec{c}}{\vec{a} \cdot (\vec{b} \times \vec{c})}$$

Reciprocal lattices are given by σ_{100} , σ_{010} & σ_{001} as they are denoted as a^* , b^* & c^* .

$$\therefore a^* = \frac{\vec{b} \times \vec{c}}{\vec{a} \cdot (\vec{b} \times \vec{c})}$$

$$\text{Similarly, } b^* = \frac{\vec{c} \times \vec{a}}{\vec{a} \cdot (\vec{b} \times \vec{c})}$$

$$c^* = \frac{\vec{a} \times \vec{b}}{\vec{a} \cdot (\vec{b} \times \vec{c})}$$

This is the relation between direct lattice & reciprocal lattice.

Properties of reciprocal lattices:-

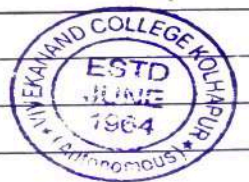
- i) The reciprocal of reciprocal lattice is a direct lattice. :-

The reciprocal lattice a^* is given by,

$$a^* = \frac{\vec{b} \times \vec{c}}{\vec{a} \cdot (\vec{b} \times \vec{c})}$$

we have to show,

$$(a^*)^* = a$$



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Q. No.



$$\therefore (a^*)^* = \frac{b^* \times c^*}{a^* \cdot (b^* \times c^*)} \quad \dots (1)$$

We know that, $a \cdot a^* = 1$

Multiply eqn (1) by $a \cdot a^*$

$$\therefore (a^*)^* = \frac{a \cdot a^* \cdot b^* \times c^*}{a^* \cdot (b^* \times c^*)}$$

$$= a \cdot \frac{a^* \cdot (b^* \times c^*)}{a^* \cdot (b^* \times c^*)}$$

$$(a^*)^* = a$$

hence we proved this

ii) The volume of unit cell in reciprocal lattice is the reciprocal of volume of unit cell in direct lattice :

$$\text{To show : } a^* \cdot (b^* \times c^*) = \frac{1}{a \cdot (b \times c)}$$

Proof :-

$$a^* \cdot (b^* \times c^*) = \left\{ \frac{b \times c}{a \cdot (b \times c)} \right\} \left\{ \frac{c \times a}{a \cdot (b \times c)} \right\}$$

$$\left\{ \frac{a \times b}{a \cdot (b \times c)} \right\}$$



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7

Q. No.



$$= \frac{1}{[a \cdot (b \times c)]^3} (b \times c) [(c \times a)(a \times b)]$$

$$= \frac{1}{[a \cdot (b \times c)]^3} (b \times c) [(c \times a) \cdot a - a \cdot (a \times b)]$$

we know that,

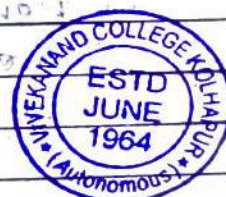
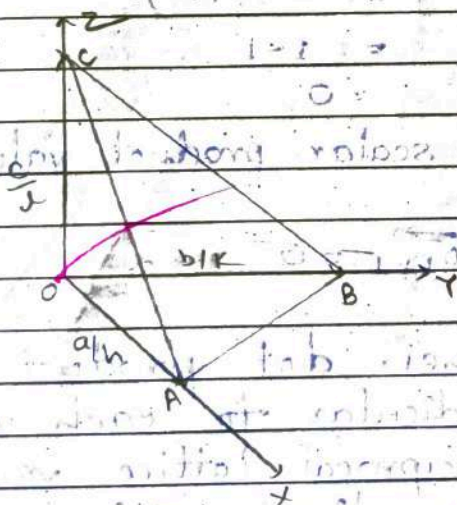
$$(c \times a) \cdot a = 0$$

$$\therefore a^* \cdot (b^* \times c^*) = \frac{1}{[a \cdot (b \times c)]^3} [a \cdot (b \times c)]^2$$

$$\therefore a^* \cdot (b^* \times c^*) = \frac{1}{a \cdot (b \times c)}$$

That is the proof.

iii) Every reciprocal lattice vector is perpendicular to direct lattice.



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Q. No.



The intercept on x-axis is,

$$OA = \vec{a}$$

The intercept on y-axis is,

$$OB = \frac{\vec{b}}{k}$$

The intercept on z-axis is,

$$OC = \vec{c}$$

From diagram,

$$\frac{\vec{b}}{k} + \vec{b} = \vec{a}$$

$$\vec{b} = \frac{\vec{a}}{h} - \frac{\vec{b}}{k}$$

$\vec{b} \cdot \vec{\sigma}_{hkl}$ be the scalar product.

$$\vec{b} \cdot \vec{\sigma}_{hkl} = \left(\frac{\vec{a}}{h} - \frac{\vec{b}}{k} \right) \cdot (ha^* + kb^* + lc^*)$$

$$= 1 - 1$$

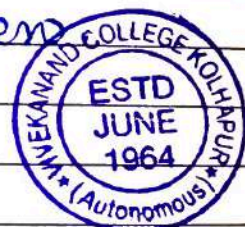
$$= 0$$

and this scalar product value is zero
similarly,

$$\vec{a} \cdot \vec{\sigma}_{hkl} = 0$$

hence as their dot product is zero, that
are perpendicular to each other.

i.e. Every reciprocal lattice vector is perpendicular
to direct lattice.



PRN - 2015010055714255



VIVEKANAND COLLEGE, KOLHAPUR

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Seat No. 853

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Information to be filled by Student (विद्यार्थ्याने भरावयाचा रकाना)

Day and Date : 23-1-018

Language of Answer : English

Examination : B.Sc. III, Internal

Question Paper Code No : _____

Subject : Physics

Paper No : _____

Section : _____

Q. No.	Examiner Marks	Moderator Marks
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Total	<u>2/25</u>	
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Marks								

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Q. No.



1

- 1) The co-ordination no. of FCC lattice is 12
- 2) The atomic radius for simple cubic lattice is $a/2$
- 3) The Miller indices of a plane which cuts the intercept of 2, 3 & 4 unit along the three axes respectively are, $6\ 4\ 3$
- 4) Diffraction of X-rays from the crystal is the phenomenon of reflection.
- 5) The volume of unit cell of reciprocal lattice is inversely proportional to volume of unit cell of direct lattice.

OS



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Q. No.

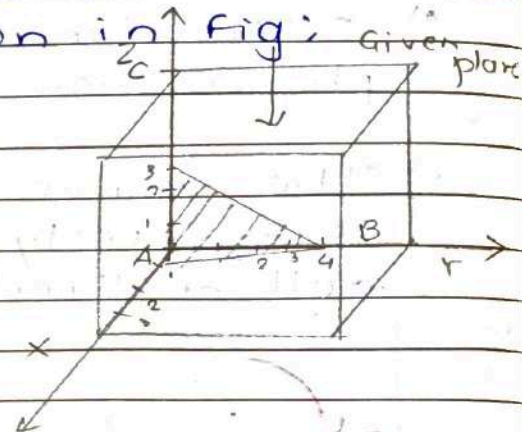
Q)



Q) In a crystal plane are defined by giving their orientation without giving position in space with reference to the direction of basis vector, plane has particular orientation, which may be defined by any three points of a plane, provided the points are not collinear.

Consider a plane having plane ABC intercept one axial unit on X axis, four axial unit on Y axis & three axial unit on the Z axis. shown in Fig:

The numerical parameter of the faces or plane are 4, 2, 3. These parameters taken as reciprocal of number. These parameters are called as Miller Indices.



Axial length	4 A	8 A	3 A
Intercept	1 A	4 A	3 A
Fractional intercept	$\frac{1}{4}$	$\frac{2}{4}$	$\frac{3}{3}$
reciprocal (Miller Indices)	4	2	1

Miller indices of ABC plane (4, 2, 1)
denoted by hkl in parenthesis is
(hkl) = (4, 2, 1)



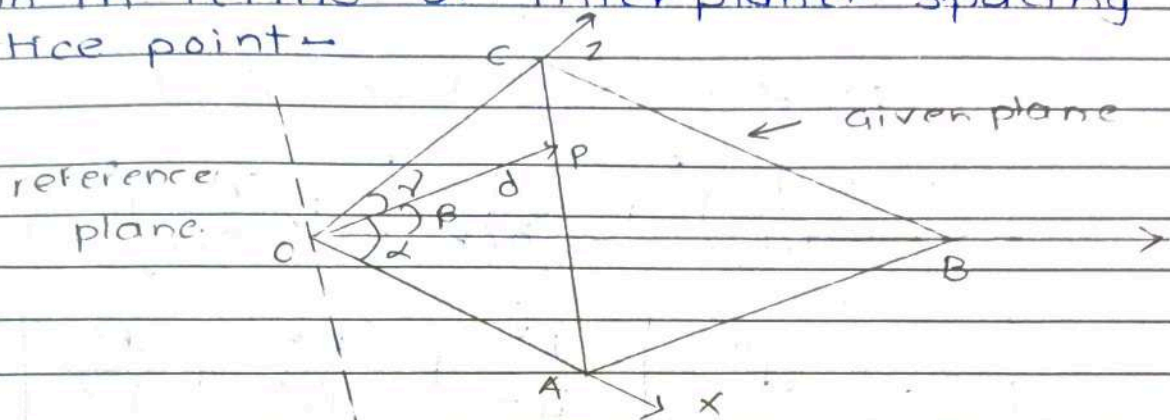
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5

Q. No.



Relation in terms of inter planer spacing and lattice point →



Consider the axis x, y, z mutually perpendicular to each other.

Consider a reference plane passes through origin & next plane ABC cuts on the intercept a/h on x axis, b/k on y axis and c/l on z axis.

let d be perpendicular distance betⁿ reference plane & given plane.

let (h, k, l) be miller indices of given plane. let α be the angle betⁿ normal and OA , β be angle betⁿ normal & plane OB & γ be angle betⁿ normal & plane OC .

let $\cos \alpha, \cos \beta, \cos \gamma$ be the direction angle betⁿ of normal plane

by geometry in ΔAOB ,

$$\cos \alpha = \frac{d}{a/h}$$

$$\cos \beta = \frac{d}{b/k}$$

$$\cos \gamma = \frac{d}{c/l}$$



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Q. No.



by using the property of triangle, trigonometry

$$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$$

$$\therefore \left(\frac{d}{a/h} \right)^2 + \left(\frac{d}{b/k} \right)^2 + \left(\frac{d}{c/l} \right)^2 = 1$$

$$\therefore d^2 \left[\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2} \right] = 1$$

$$\therefore d^2 = \frac{1}{\left(\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2} \right)}$$

$$\therefore d = \sqrt{\frac{1}{\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2}}}$$

special case -

For cubic system,
 $a = b = c$

$$\therefore d = \sqrt{\frac{1}{\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2}}}$$

$$d = \frac{a}{\sqrt{h^2 + k^2 + l^2}}$$





VIVEKANAND COLLEGE, KOLHAPUR

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Day and Date : 23/11/2018

Language of Answer : English

Examination : Bsc III, Internal

Question Paper Code No : _____

Subject : Physics

Paper No. : Paper XVI

Section : _____

Jr. Supervisor's Sign :
Students Sign : <u>RS</u>
Seat No. <u>8506</u>
Seat No. in words _____
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Q. No.	Examiner Marks	Moderator Marks
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Q. No.



Q-1

- i) a) 12 ✓
- ii) a) $9/2$ ✓
- iii) a) ~~(6, 4, 3)~~ a) (6 4 3) ✓
- iv) a) scattering ✓
- v) b) inversely proportional to volume of unit cell. ✓



Q. No.					TOTAL					TOTAL
Marks										

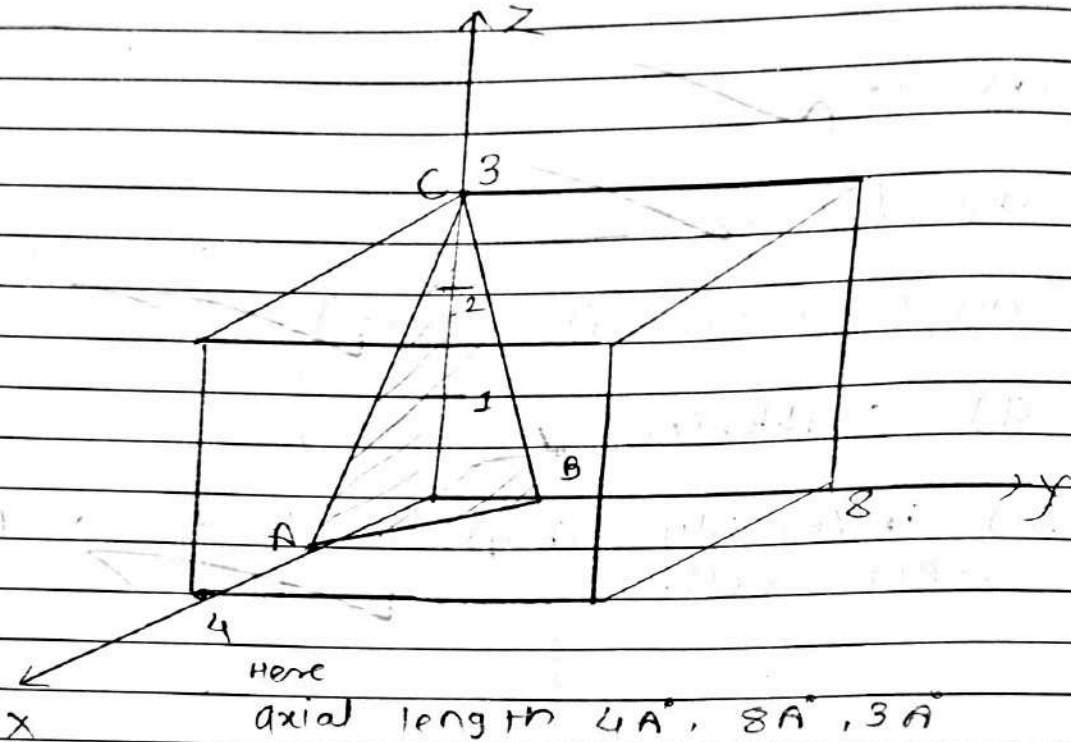
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Q. No.

Q. 2.

ii)



Defination:-

Orientation of a plane in a crystal can be described in terms of there reciprocal of intercept on 3 axis.

Consider a plane ABC having intercept one axial unit on x axis, 4 axial unit of y axis & 3 axial unit on z axis as shown in fig.

The numerical parameter of the plane are , 1, 4 & 3 but according to Miller it is more useful to denote or discribe this parameters by taking reciprocal of its numerical value.



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Marks								

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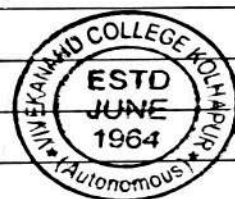
This parameters are called as 'Miller indices'.

Axial length	4 A	8 A	3 A
Intercept	1 A	4 A	3 A
Fractional intercept	$\frac{1}{4}$	$\frac{1}{8}$	$\frac{3}{3}$
Reciprocal miller indices.	4	2	1.

Miller indices of ABC plane are (4 2 1) denoted by h k l that is

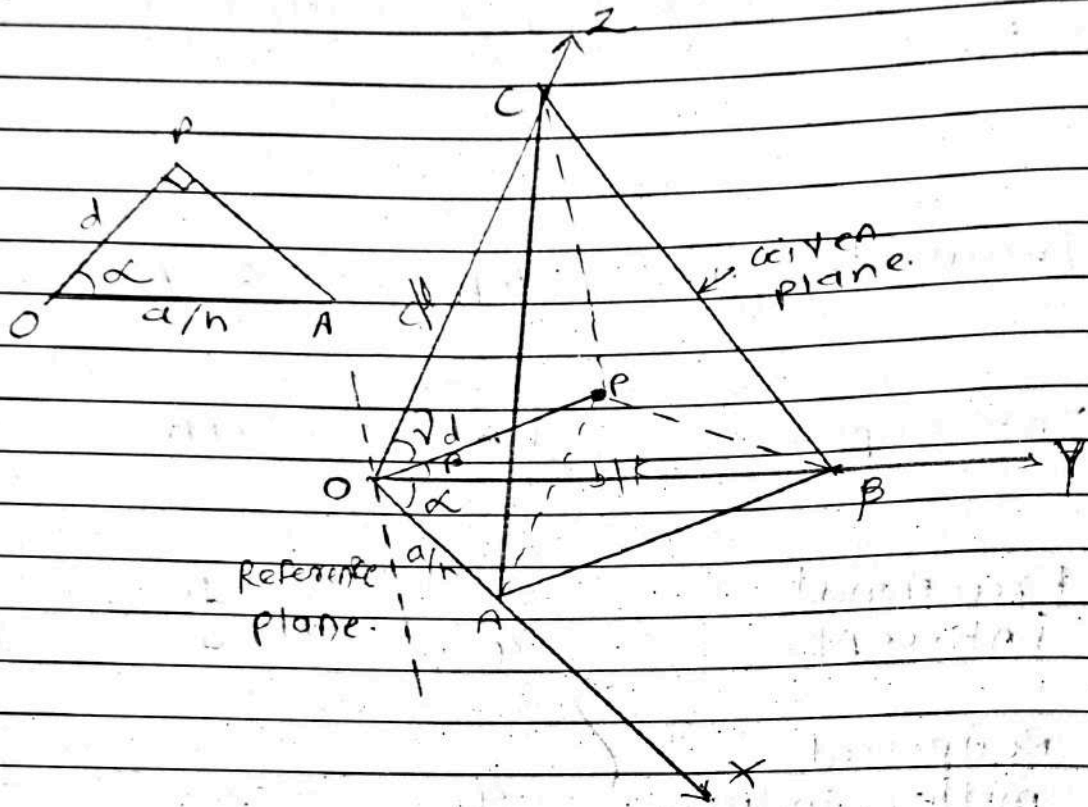
$$(h \ k \ l) \equiv (4 \ 2 \ 1)$$

Now, relation in terms of interplanar spacing and lattice parameters.



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Q. No.



$$l(OA) = a/h$$

$$l(OB) = b/k$$

$$l(OC) = c/l$$

Consider the axis XYZ mutually perpendicular to each other.

Consider the reference plane passes through the origin of the other plane ABC cuts the plane intercept a/h on X axis, b/k on Y axis & c/l on Z axis. a normal AP is drawn to the plane ABC from the origin.



Q. No.				TOTAL				TOTAL
Marks								

Q. No.



Let, 'd' be the perpendicular distance betⁿ reference plan & given plane.

Let, (h k l) miller indices of given plane ABC.

Let, α' be the angle betⁿ normal & OA

β = angle betⁿ normal & OB

γ = angle betⁿ normal & OC.

Let $\cos \alpha$, $\cos \beta$, $\cos \gamma$ be the direction cosine of normal.

By using geometry,

$$\cos \alpha = \frac{d}{a/h}$$

$$\cos \beta = \frac{d}{b/k}$$

$$\cos \gamma = \frac{d}{c/l}$$

$$\text{But } \cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$$

$$\left(\frac{d}{a/h} \right)^2 + \left(\frac{d}{b/k} \right)^2 + \left(\frac{d}{c/l} \right)^2 = 1$$



Q. No.					TOTAL				
Marks									



Q. No.

$$\frac{d^2 h^2}{a^2} + \frac{d^2 k^2}{b^2} + \frac{d^2 l^2}{c^2} = 1$$

$$d^2 \left[\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2} \right] = 1$$

$$d^2 = \frac{1}{\left[\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2} \right]}$$

$$d = \frac{1}{\sqrt{\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2}}}$$

this is the relation betⁿ interplaner distance & miller indices.

Case 1:-

For cubical System

$$a = b = c$$

$$\therefore d = \frac{1}{\sqrt{\frac{h^2}{a^2} + \frac{k^2}{b^2} + \frac{l^2}{c^2}}}$$

$$d = \frac{1}{\sqrt{\frac{h^2 + k^2 + l^2}{a^2}}}$$

